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(and others)

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Vehicle Integrated Prognostic Reasoner (VIPR)

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Acknowledgements

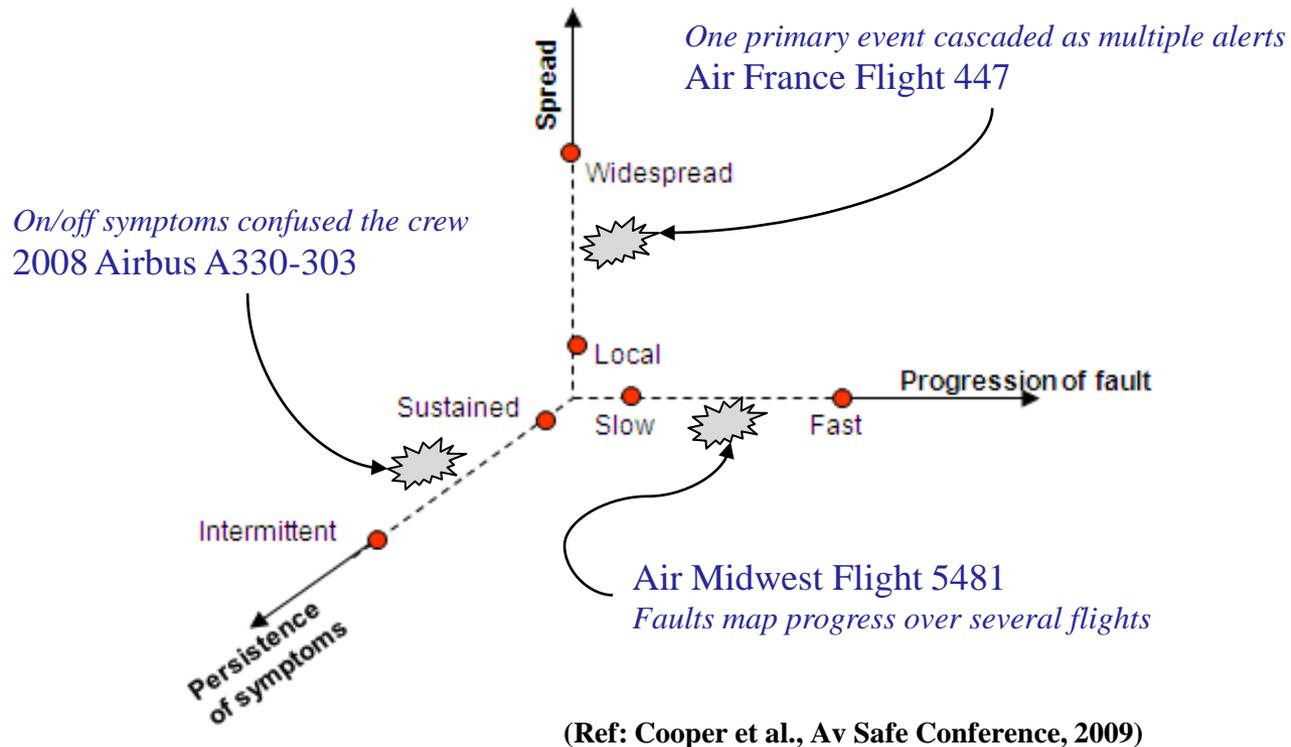
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Outline

- Motivation: Role of vehicle level reasoning system (VLRS) in aviation safety
- Phase-1: Vehicle Integrated Prognostic Reasoner (VIPR)
 - user requirements, concepts, architecture, protocols, validation data
- Phase 2: Theory and implementation
- Closing remarks

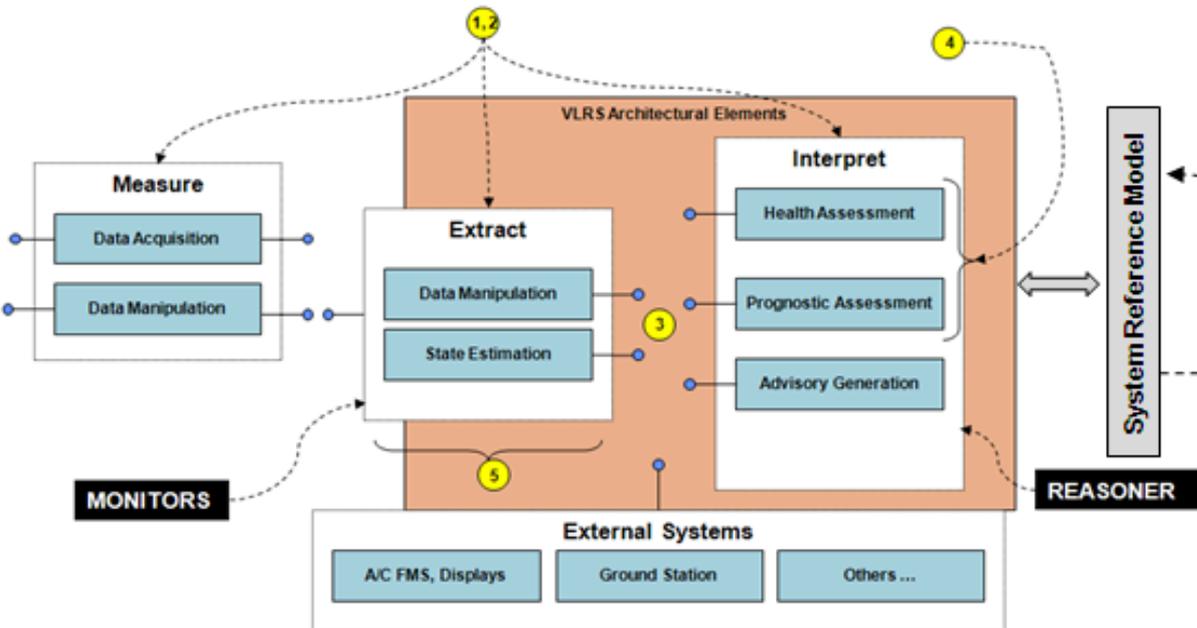
Capturing safety events

- An aircraft consists of several subsystems. Propulsion, flight management, bleed, etc. All these have subsystems have basic-level diagnostic monitors
- New Interactions may emerge, hence operational data provides a source of constant learning



Large number of heterogeneous, synchronous and asynchronous evidence needs to be reasoned across to entire vehicle to determine its actionable state – namely Vehicle Level Reasoning System (VLRS)

Data Driven VLRS



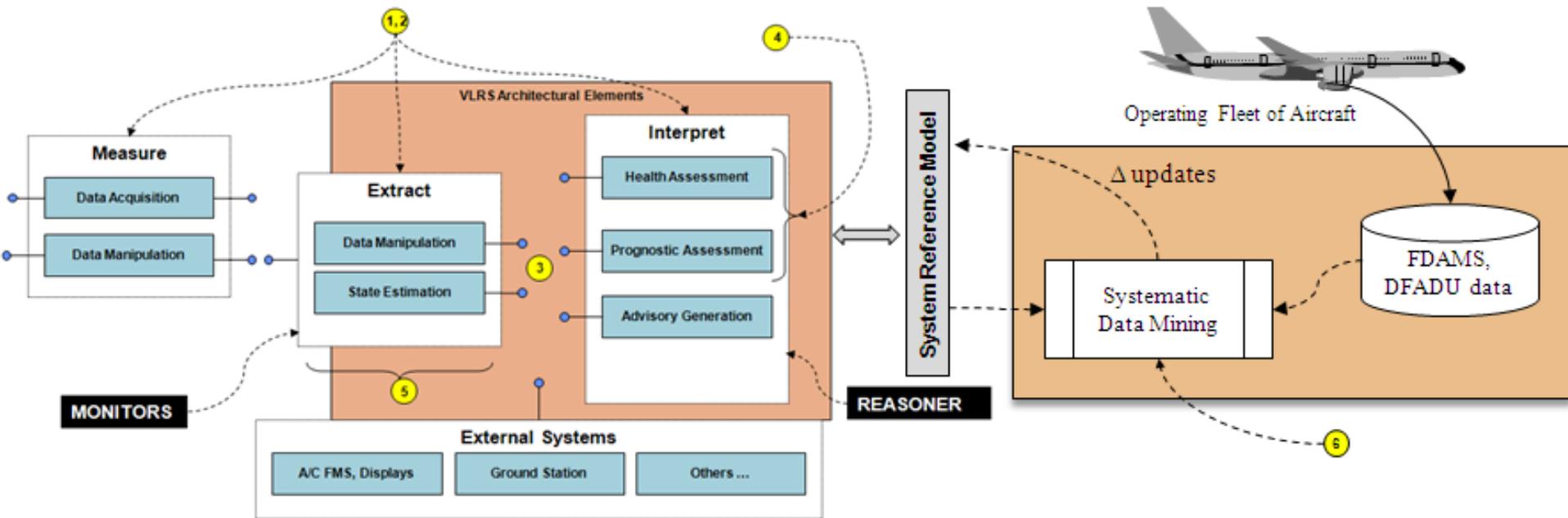
Current state of the ART:

- Honeywell's ADMS = Aircraft Diagnostic & Monitoring System.
- Onboard the B777, B787, Embraer, Dassault.

Data Driven:

- Clear separation between monitors (evidence generation), reference model that encodes aircraft specific configuration and the reasoning engine (evidence interpretation)

Data Driven VLRS+

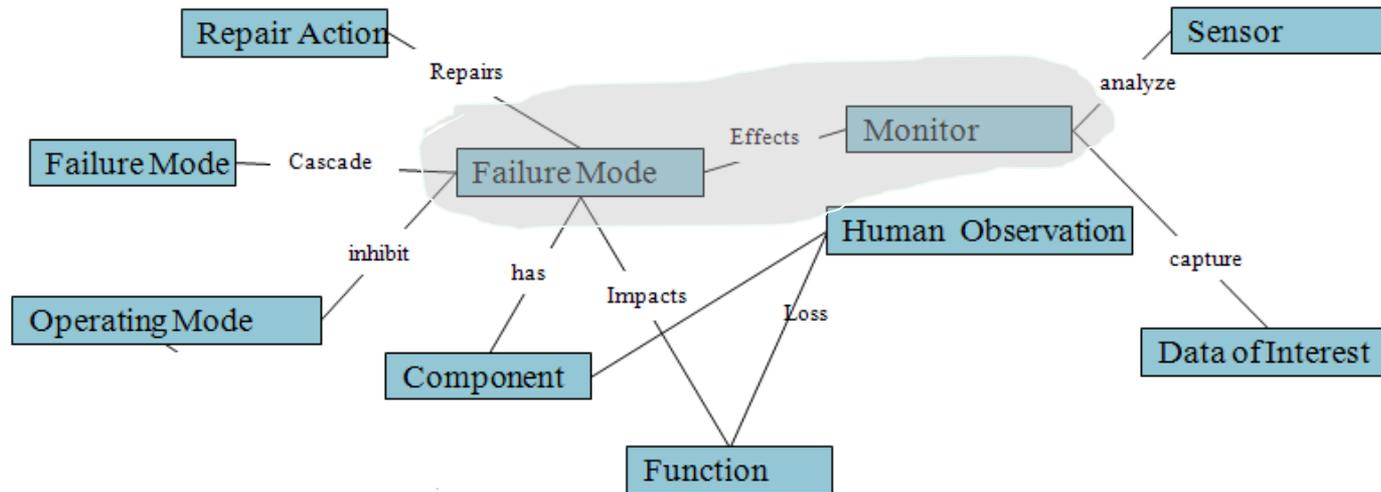


Next Generation VLRS needs to support the following features

- Support temporal and prognostic reasoning
- Active role for fault isolation
- Systematic updates to the reference model using operational data – continual learning

Working with NASA to provide systematic extensions to the field-proven ADMS reasoner to handle next gen safety requirements – called VIPR

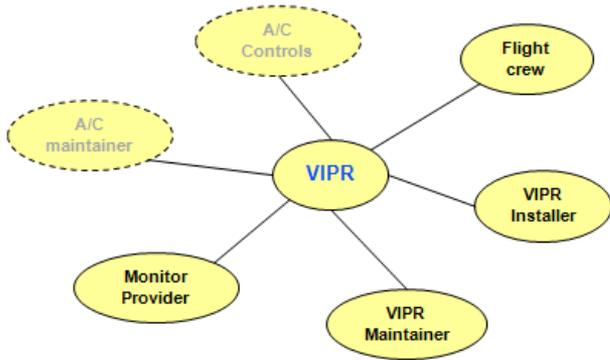
System Reference Model



- *Data is provided by individual member system (engines, avionics, landing, etc, ...) suppliers and the aircraft model is assembled by an integrator or VLRS provider*
- *Accuracy and coverage depends on quality of evidence and completeness of interaction capture*

System Reference Model (static) is a network that captures the specific aircraft configuration for VIPR

User Requirements



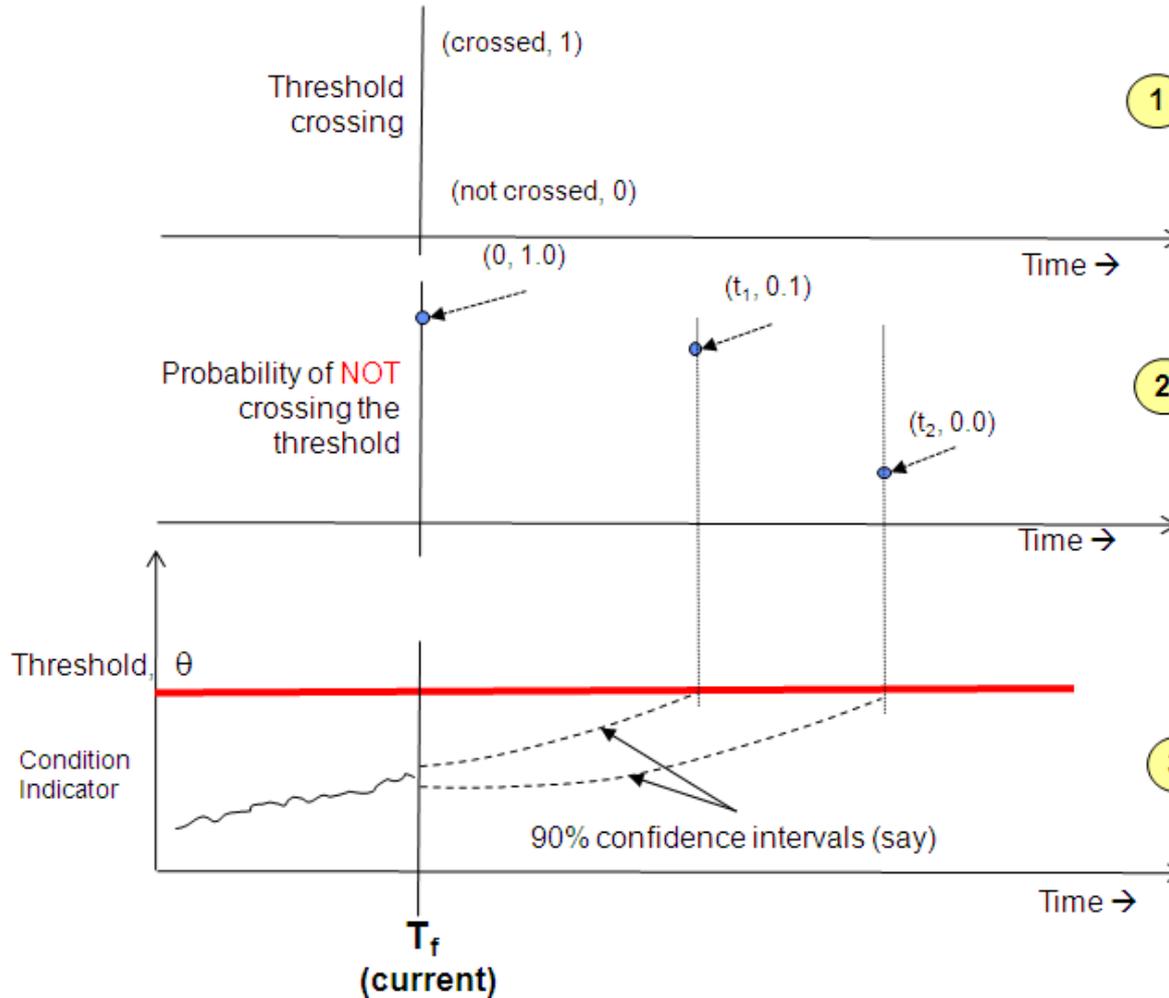
	Event Type	Top Level requirements (Flight crew)
Time Evolution	Slow	1. Less important. 2. Important, if and only if it will affect the current flight.
	Fast	1. Very important. Early detection of incipient conditions. 2. Quick identification of (and subsequent) (air traffic control) actions
Impact Propagation	Localized	1. Detect events in real time. 2. If impact is localized, confirm that backup is working as designed
	Widespread	3. Keep track of intermittents 4. Remove the evidence.
Intermittence	Constant	5. Order.

1. Detect events in real time.
2. If impact is localized, confirm that backup is working as designed
3. Keep track of intermittents

	Top Level requirements (VIPR Installer)	tion and establish that intermittency is true. not cause may be less important
Scalability	1. Separate the reasoning algorithms from aircraft specific configurations. 2. A common code base is easy to validate and makes is easier to certify. 3. Finite set of operations, each of which is bounded computationally.	
Deployment	1. Reason 2. Support 3. VIPR sh 4. Unamb	1. generating monitors. 2. of a monitor provider. 3. tation.
Accuracy	1. Ability t 2. Must in used as 3. States a 4. Capable of proposing and working with multiple fault hypotheses.	1. s important. 2. t can be archived and 3. / operations

1. Allow member systems to encode proprietary knowledge.
2. Common code base to reduce certification efforts.
3. Work within aircraft HW/SW constraints

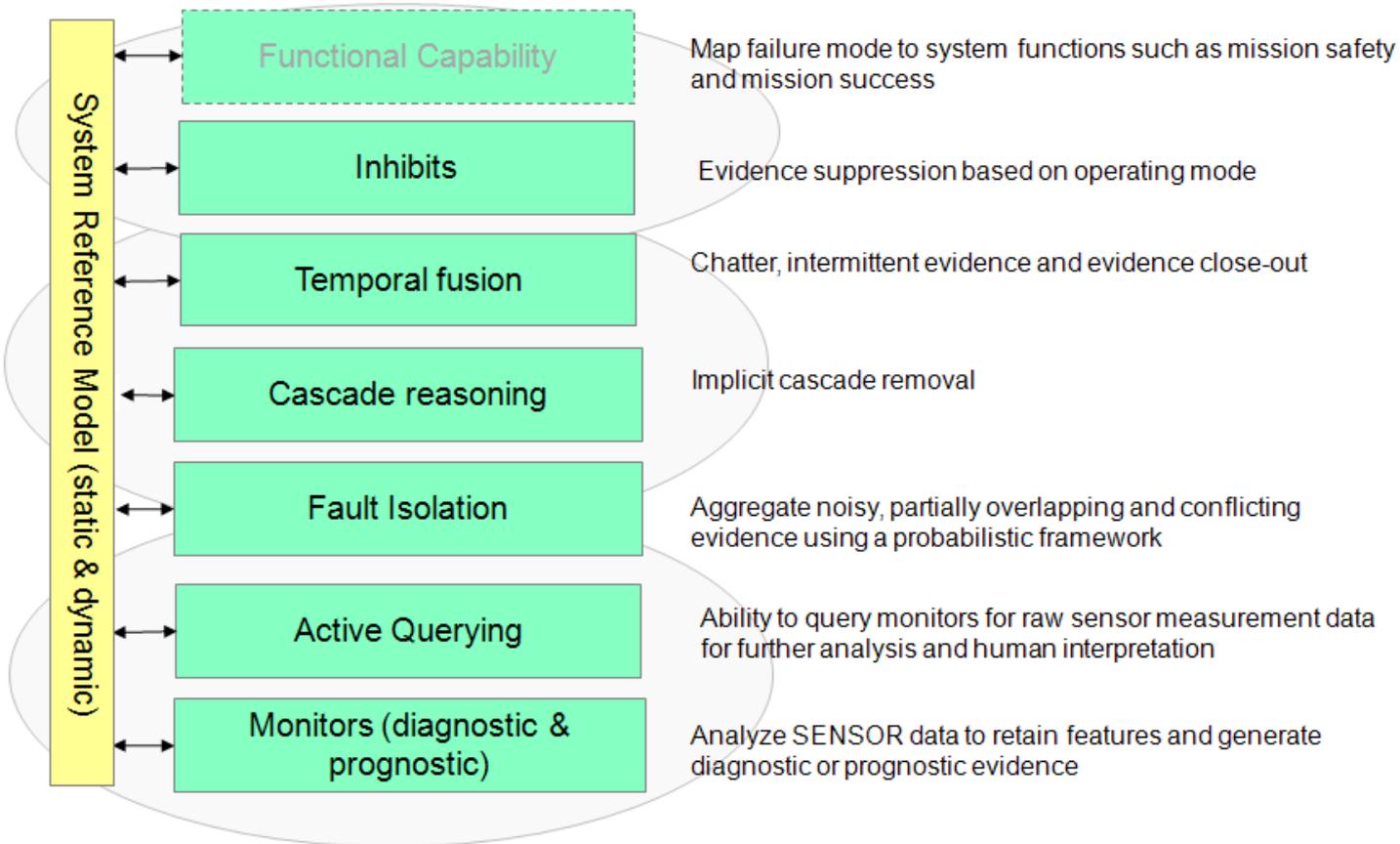
Three forms of monitors/ Evidence Abstraction



- 1 Supplier can provide 0/1 threshold crossing or diagnostic monitor
 - Supports prognostic reasoning
- 2 Supplier can provide future crossings or prognostic monitor
 - More IP exposure
 - Supports active query
- 3 Supplier can provide time-series CI along with a threshold or parametric monitor

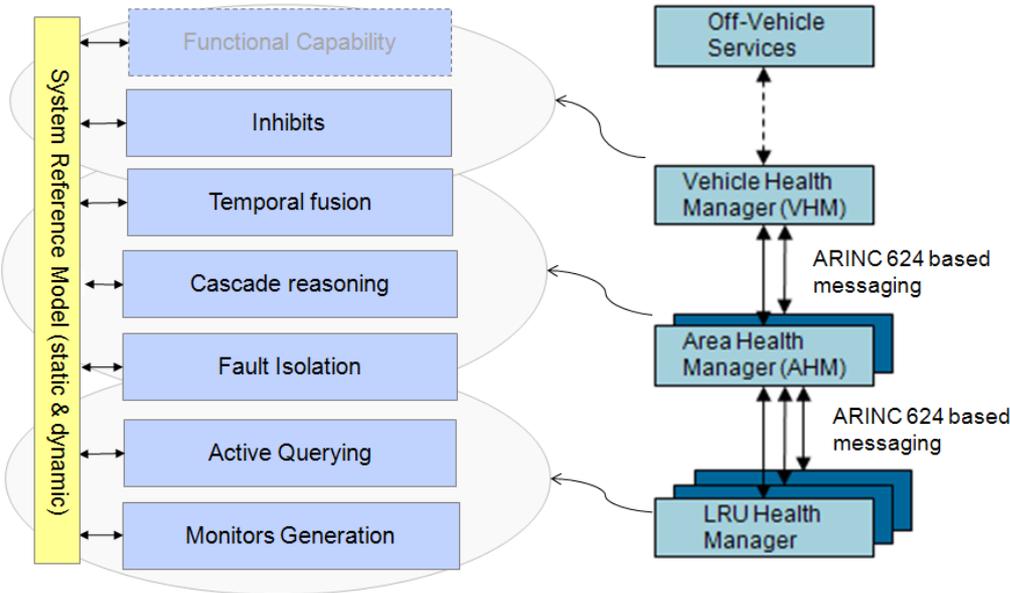
VIPR brings in more advanced heterogeneous evidence

Sub-functions within VLRS



Modular functions to solve the overall VIPR problem – namely health state isolation and prediction

Layered Computation Architecture

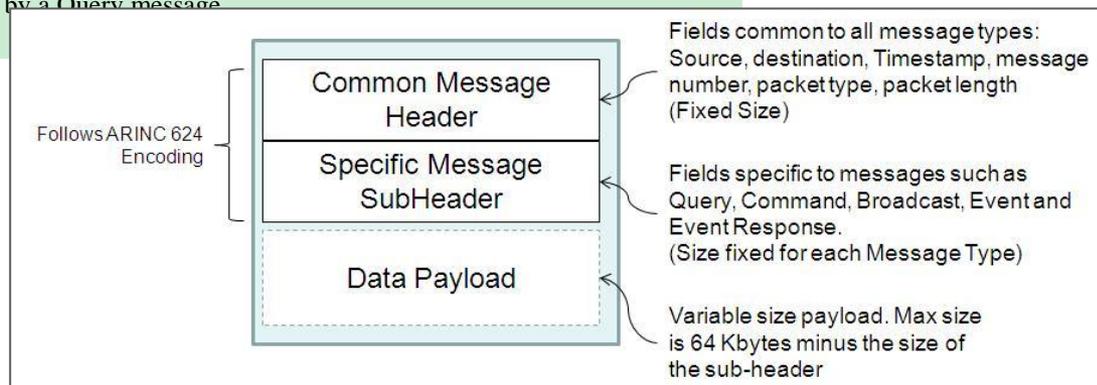


- In an aircraft:
 - A LRU may not be capable of generating monitors
 - VIPR needs to provide computational resource to generate these monitors based on sensor data
 - Hence the need for a LRU health manager tier to support these intensive calculations
 - Area Health Manager does most of the fault isolation
 - Vehicle health manager does inhibits, temporal and functional capability assessment
- Practically:
 - VIPR like any other CBM system needs to buy itself. Customer may only choose one or more functions, rather than the entire thing!

A distributed reasoning architecture allows VLRS to operate within aircraft computation constraints

Messaging protocols

Message Type	Description
Broadcast	Broadcast messages are of interest to multiple elements and contain such information as flight phase and time.
Command	Command messages to operate the vehicle are issued from VHM and maintenance crew. Acknowledgment is sent from receiver and often contains data response.
Event	CONCLUSIONS sent to higher-level health managers as events. Messages contain originator, event type, time, location, analysis and supporting data. Includes Status, Capability, Maintenance, and Event Observe/Orient/Decide messages.
Query	Query messages can request additional data.
Command Response	Acknowledges the receipt of a command. Can include data confirming the results of the command.
Event Response	Acknowledges the receipt of an event message.
Query Response	Provides the data requested by a Query message.



ARINC 624 messages encoding to support VIPR communications

Aircraft Data

- We instrumented aircrafts to record 180+ parameters at 1, 2, 4, 8 and 16 Hz over the entire the flight cycle
 - Fleet consisted of 30+ identical airplanes and flies 2—3 flights each day
 - Access to 3000+ consecutive flights

Event Date	Safety Incident	Event Date	Safety Incident	
30-Aug-06	Loss of oil and engine shutdown	5-Mar-05	Pilot error	✗
1-Aug-06	Vibration, engine shutdown, Turbine damaged	11-Jan-05	Hydraulic leak, smoke in the cabin	?
26-Jan-06	Over speed temperature and engine shutdown	5-Jul-03	Incipient ice formation	
20-Oct-05	Hydraulic leak. Take off aborted	3-Sep-02	Runway incident. Hit a pole	✗
15-Aug-05	Intermittent engine on fire. Traced to fuel problems	19-Jul-02	Runway incident, hit a catering truck	✗
17-Apr-05	False alarm of engine on fire. Fuel leakages			

ASIAS (FAA's safety reporting website) incidents and 1—16 Hz aircraft parametric data surrounding these incidents

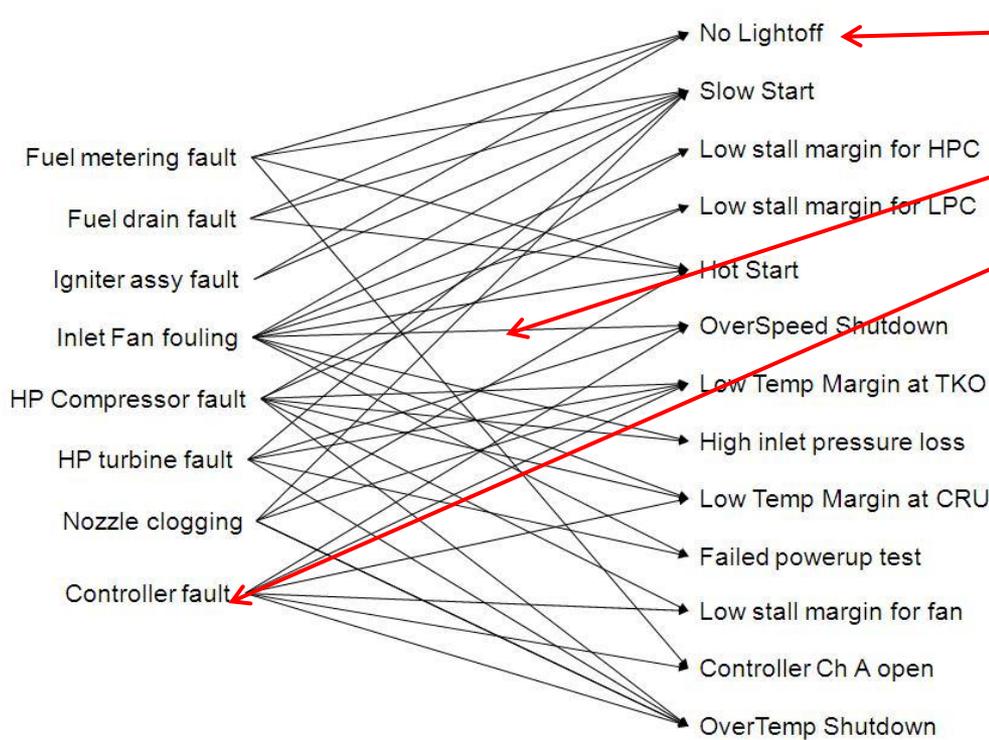
Three Steps (phase)

- Phase 1: concepts, design, concept of operations
 - Establish initial design and pathway for acceptance within the community, availability of historic data
- Phase 2: detailed design, implementation and validation
 - Demonstration in a simulation environment, tools & methods
- Phase 3: metrics collection
 - Scenario-based cost, prognostic benefit and safety impact metrics calculation

The Reasoner theory

Failure modes (causes)

Monitors (symptoms)



$$P(m_j=1 \mid \text{no failure})$$

$$P(m_j=1 \mid fm_i=1)$$

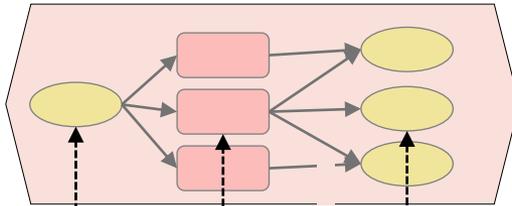
$$P(fm_i=1)$$

As new monitors “fire”, they get assigned a 1 (indict) and 0 (exonerate) state. Net result: calculate joint probability of a failure mode occurring and observing various monitors. That is, $P(fm_j = 1, m_1 = 1, m_2 = 1, m_3 = 0, \dots)$

Use a noisy-or (Naïve Bayesian update) to calculate the joint probability

Reasoner Engine: States & Operators

Fault Condition FC – VIPR state



Initiating Monitor

Failure modes that could trigger this monitor $AG(FC)$

Monitors expected to fire if any of the failure mode is active, $EoI(FC)$

- Represents a “diagnostic conclusion within VIPR”
- Contains an ambiguity set of failure modes
- Tracks a single fault i.e. makes a single fault assumption hypothesis
- VIPR can contain several fault conditions at any time

VIPR “state update operators”

Probability update: $P(fm_j = 1, m_1 = 1, m_2 = 1, m_3 = 0, \dots)$

Isolate: $P(fm_j = 1, \dots) > \delta_I + P(fm_k = 1, \dots), \dots$

Splitting: $P(fm_j = 1, fm_k = 1, \dots) > \delta_S + P(fm_j = 1, \dots), P(fm_k = 1, \dots)$

Merging: $EoI(FC_1) = EoI(FC_2)$

FM Addition: $AG(FC) \leftarrow AG(FC) + fm_j$

FM Removal: $AG(FC) \leftarrow AG(FC) - fm_j$

Active Query: ? m_i, m_i in $EoI(FC)$

Closing: $P(fm_j = 1, \dots) < \delta_0$

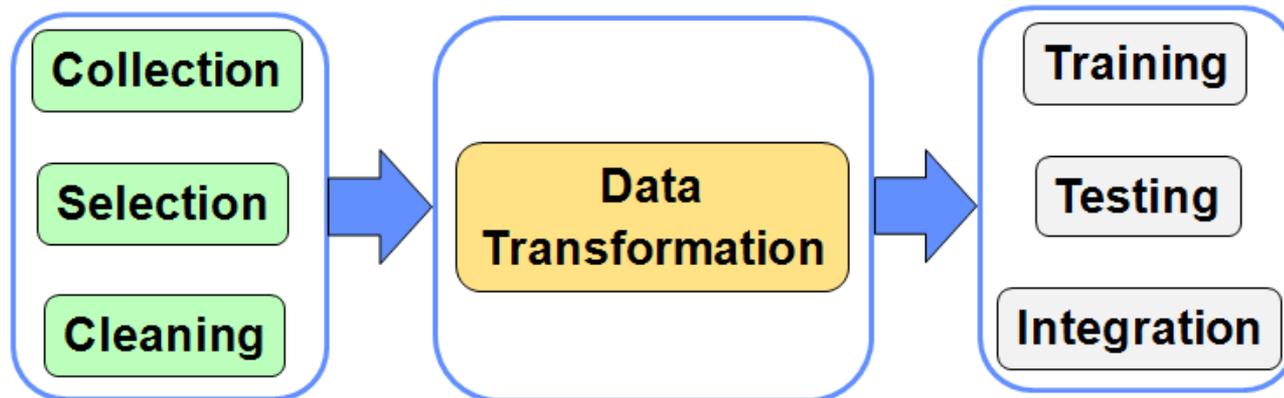
Ranking: $\text{sort}(P(fm_j = 1, \dots))$

Deletion: $\text{time}(P(fm_j = 1, \dots)) > NTE$

- Reasoner can track multiple simultaneous faults
- Update is “event driven” – triggered by arrival of new monitor
- A finite (deterministic) set of operators per update cycle
- Contains several user-tunable knobs or constants to trade-off sensitivity (highlighted in bold)

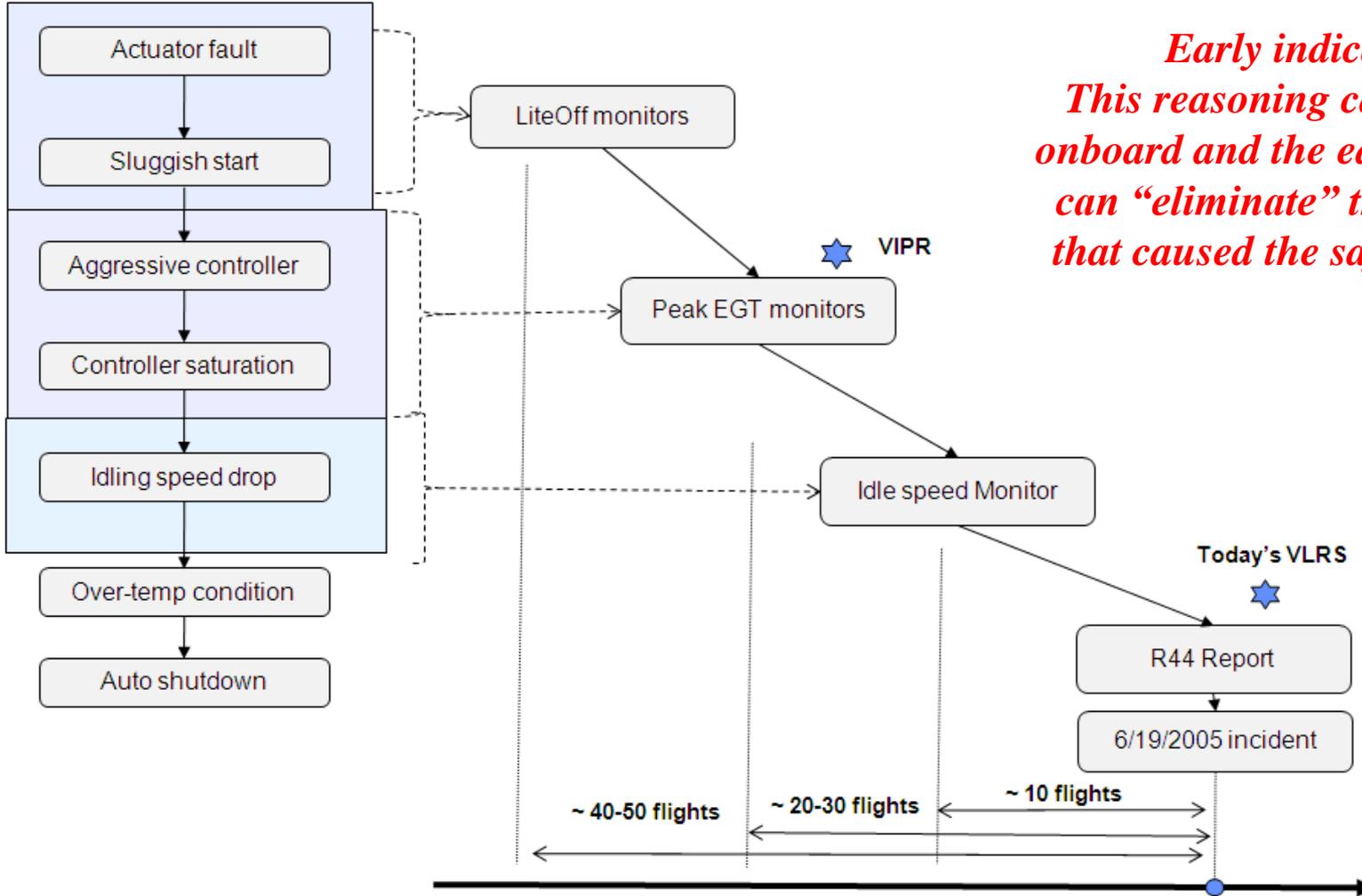
Goals of the Data Mining Work

- Demonstrate a systematic approach for continual improvement in the VIPR performance
 - Exploit data from past adverse event occurrences and known fault situations
 - Semi-automated data-driven processes
 - Selective Data mining operations



curation

Impact on Safety



*Early indication
This reasoning can be done
onboard and the early indication
can “eliminate” the root cause
that caused the safety incident.*

Closing Remarks

- Vehicle level reasoner is aimed at:
 - **Improving aircraft safety** due to enhanced monitoring and reasoning about the aircraft's health state
 - **Operational cost savings** by enabling Condition Based Maintenance (CBM)
- In this talk, we outlined the next gen VLRS – namely VIPR
 - **Trade space**: user requirements and safety drivers, delta-increments from baseline to realize the advanced functions of VLRS
 - **Reasoning steps**: defined the steps for evidence aggregation, fault hypothesis management, using an abductive reasoning framework
 - **Role of Data mining**: defined algorithmic approach to update the capture new information